

## Lotus Plug&Play kit



Racing Data Power

## INTRODUCTION

The P&P kit specifically designed for Lotus – including an **ECU Bridge** with an OBDII connector for immediate plug into the engine control unit (ECU) network – makes **SmartyCam** connection and activation very easy.

In fact, it is enough to connect the **ECU Bridge** to the vehicle socket – as detailed in this document – to get the key values from the engine control unit and record/overlay them on **SmartyCam** videos.

## Index

|   |           |
|---|-----------|
| <b>Chapter 1– Kit and optionals .....</b>                           | <b>4</b>  |
| 1.1 – The kit .....   | 4         |
| 1.2 – The optionals.....  | 4         |
| <b>Chapter 2 – Preliminary information .....</b>                    | <b>5</b>  |
| 2.1 – Car Models and communication protocol.....                    | 5         |
| 2.1.1– <i>OBDII CAN (15765/4) protocol .....</i>                    | <i>5</i>  |
| 2.1.2 – <i>OBDII K Line (ISO9141/2) protocol .....</i>              | <i>5</i>  |
| 2.1.3 – <i>OBDII KWP2000 Fast Init (ISO 14230/4) protocol .....</i> | <i>5</i>  |
| 2.2 – Lotus OBDII connector position .....                          | 5         |
| <b>Chapter 3 – Connections.....</b>                                 | <b>6</b>  |
| 3.1 – Connecting SmartyCam to ECU Bridge .....                      | 6         |
| 3.2 – Connecting ECU Bridge to the car .....                        | 6         |
| <b>Chapter 4 – Elise, Exige, 2–Eleven from 2004 to 2007.....</b>    | <b>7</b>  |
| 4.1 – Configuration setting .....                                   | 7         |
| 4.2 – Communication protocols.....                                  | 8         |
| 4.2.1 – <i>OBDII Protocol.....</i>                                  | <i>8</i>  |
| 4.2.2 – <i>Clusters 04-07 Protocol .....</i>                        | <i>8</i>  |
| <b>Chapter 5 – Elise, Exige, 2–Eleven since 2008.....</b>           | <b>9</b>  |
| 5.1 – Software configuration setting.....                           | 9         |
| 5.2 – Communication protocol .....                                  | 10        |
| <b>Chapter 6 – Europa 2006+ and Elise S2 Rover 2001-2004.....</b>   | <b>11</b> |
| 6.1 – Software configuration setting.....                           | 11        |
| 6.2 – Communication protocol .....                                  | 12        |
| <b>Chapter 7– Evora since 2009 .....</b>                            | <b>13</b> |
| 7.1 – Software configuration setting.....                           | 13        |
| 7.2 – Communication protocol .....                                  | 14        |
| <b>Appendix – Part numbers .....</b>                                | <b>14</b> |

## Chapter 1– Kit and optionals

### 1.1 – The kit

The kit includes:



- 1 – **SmartyCam**; (1)
- 1 – **ECU Bridge** with car adapter; (2)
- 1 – 2m or 4m CAN cable;(3)

### 1.2 – The optionals

The optionals (see below) are 2 different installation kits and – to improve audio quality – the external microphone.



Suction cup kit:

- 1 – ball head
- 1 – 60 mm. arm
- 1 – suction cup
- 1 – washer



Roll-bar kit:

- 1 – ball head
- 1 – 60 mm. arm
- 1 – roll bar bracket
- 1 – washer



CAN cable with external microphone

## Chapter 2 – Preliminary information

Lotus cars can support one of these OBDII diagnosis protocols: K Line (ISO9141/2), CAN (ISO 15765/4) or KWP2000 Fast Init (ISO 14230/4). Please check below which is the appropriate protocol for each model.

### 2.1 – Car Models and communication protocol

Lotus cars support CAN (ISO 15765/4) OBDII diagnosis protocols. This protocol is supported by all Lotus models since 2008 (2-Eleven excluded).

#### 2.1.1 – OBDII CAN (15765/4) protocol

CAN (ISO 15765/4K) protocol is supported by the following models:

- all Elise models since 2008
- all Exige models since 2008;
- all 2-Eleven since 2008;
- Evora since 2009

#### 2.1.2 – OBDII K Line (ISO9141/2) protocol

K-Line (ISO9141/2) protocol is supported by the following models

- all Elise models from 2004 to 2007
- all Exige models from 2004 to 2007;
- 2-Eleven since 2007;
- Elise S2 Rover from 2001 to 2004

#### 2.1.3 – OBDII KWP2000 Fast Init (ISO 14230/4) protocol

KWP2000 (ISO14230/4) protocol is supported by the following models:

- all Europa models since 2006

### 2.2 – Lotus OBDII connector position

Lotus OBDII black connector is placed on the driver's side, below the dashboard on the vertical central console – see below:



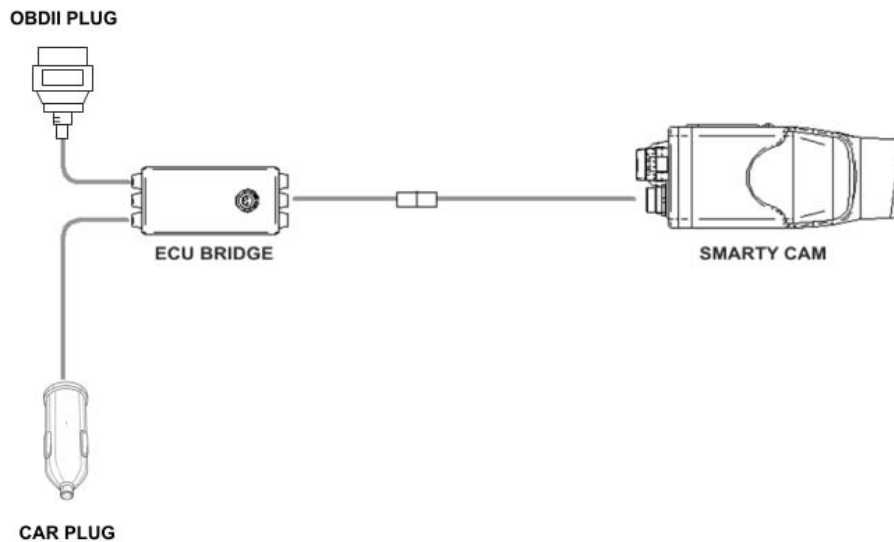
## Chapter 3 – Connections

To receive the info provided by the vehicle ECU it is necessary to connect:

**Step 1 – SmartyCam to ECU Bridge**

**Step 2 – ECU Bridge to the vehicle**

The image below shows the connections .



### 3.1 – Connecting SmartyCam to ECU Bridge

To connect **SmartyCam** to **ECU Bridge**:

- Connect the 7 pins connector placed on the **SmartyCam** back to the 2m or 4m power cable + CAN supplied with the kit.

### 3.2 – Connecting ECU Bridge to the car

To connect **ECU Bridge** to the vehicle:

- plug ECU Bridge OBDII male connector into OBDII socket (see image below);
- put the car adapter in the car cigarette lighter socket.





## Chapter 4 – Elise, Exige, 2–Eleven from 2004 to 2007

### 4.1 – Configuration setting

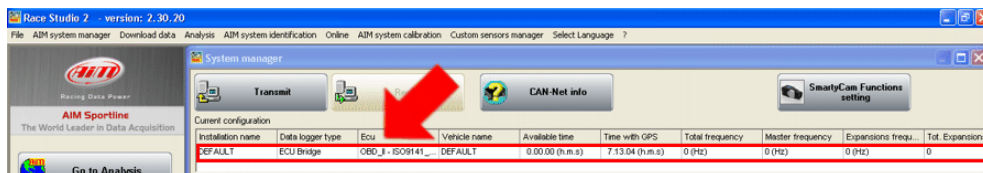
Once **ECU Bridge** is connected, it is necessary to configure it in **Race Studio 2** software. Please refer to Chapter 1 to check which is the appropriate communication protocol. Then:

- Launch **Race Studio2 Configuration** Software
- Create a configuration pressing **“New”**.

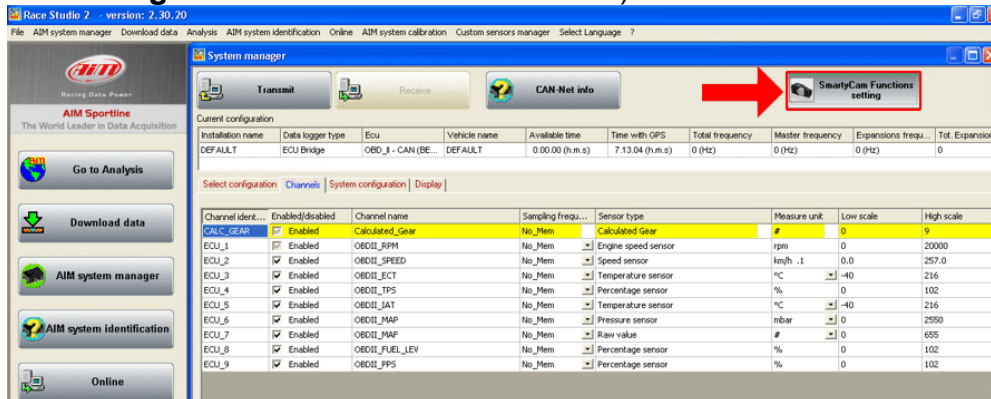


Depending on the parameters to visualize, it is possible to choose between 2 different configurations. Please refer to “Communication protocols” chapter to check the more appropriate configuration.

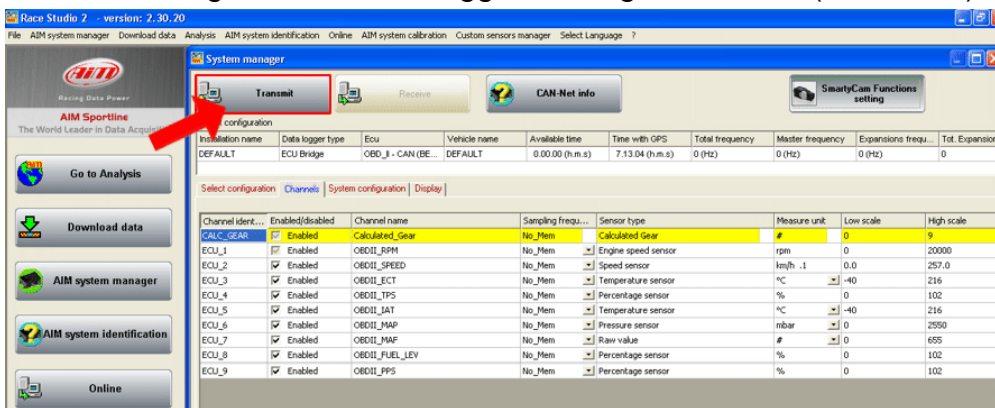
- select from **“ECU manufacturer”** menu: **“OBD\_II”** or **“LOTUS”**;
- select from **“ECU Model”** menu: **“ISO9141/2”** or **“Clusters 04-07”**



- Select **“SmartyCam Function setting”** to set **SmartyCam** channels (refer to **Race Studio Configuration** manual for more details).



- transmit the configuration to **AIM** logger clicking **“Transmit”** (see below).



**Note: it is suggested to disable non-used channels (see image above).**

## 4.2 – Communication protocols

### 4.2.1 – OBDII Protocol

Channels received by **AIM** loggers connected to OBDII are:

| <b>ID</b> | <b>CHANNEL NAME</b> | <b>FUNCTION</b>            |
|-----------|---------------------|----------------------------|
| ECU_1     | OBDII_RPM           | Engine Speed               |
| ECU_2     | OBDII_SPEED         | Speed Value                |
| ECU_3     | OBDII_ECT           | Engine Coolant Temperature |
| ECU_4     | OBDII_TPS           | Throttle Position Sensor   |
| ECU_5     | OBDII_IAT           | Intake Air Temperature     |
| ECU_6     | OBDII_MAP           | Manifold Absolute Pressure |
| ECU_7     | OBDII_MAF           | Mass Air Flow              |
| ECU_8     | OBDII_FUEL_LEV      | Fuel Level                 |
| ECU_9     | OBDII_PPS           | Pedal Position Sensor      |

**Note: all the above channels are managed by AIM OBDII. Please consider that acquired channels depend on the car model; for this reason some of them could not be available. Moreover it is suggested to disable the error channels to allow a faster data transmission.**

### 4.2.2 – Clusters 04-07 Protocol

Channels received by **AIM** loggers using Clusters 04-07 protocol are:

| <b>ID</b> | <b>CHANNEL NAME</b> | <b>FUNCTION</b>                     |
|-----------|---------------------|-------------------------------------|
| ECU_1     | CU_SPEED            | Speed value                         |
| ECU_2     | CU_RPM              | Engine speed                        |
| ECU_3     | CU_FUEL_IST         | Fuel level                          |
| ECU_4     | CU_FUEL_AVE         | Fuel average                        |
| ECU_5     | CU_ENGT             | Engine coolant temperature          |
| ECU_6     | CU_SF_LIGHT         | Shift light                         |
| ECU_7     | CU_MIL_LIGHT        | Malfunction Indicator limiter light |
| ECU_8     | CU_OIL_LIGHT        | Oil light                           |
| ECU_9     | CU_TC_LIGHT         | Traction control light              |



## Chapter 5 – Elise, Exige, 2–Eleven since 2008

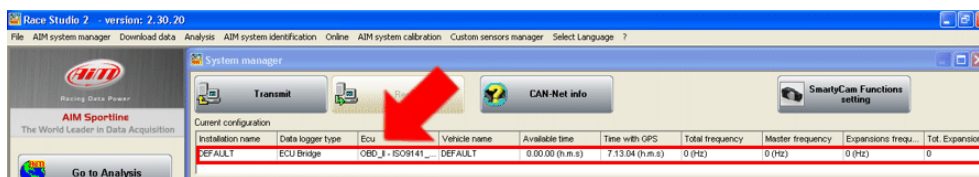
### 5.1 – Software configuration setting

Once **ECU Bridge** is connected, it is necessary to configure it in **Race Studio 2** software. Please refer to Chapter 1 to verify which is the appropriate communication protocol. Then:

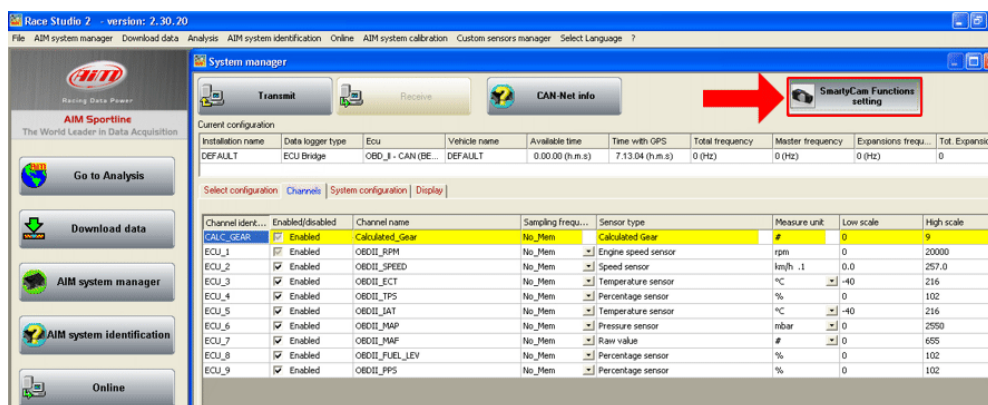
- Launch **Race Studio2 Configuration** Software
- Create a configuration pressing **“New”**.



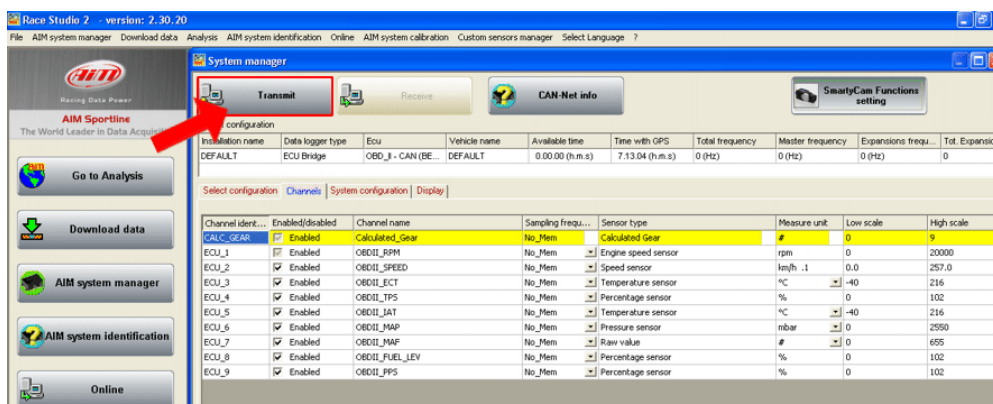
- select from **“ECU manufacturer”** menu: **“LOTUS”**;
- select from **“ECU Model”** menu: **“Clusters 08-09”**.



- Select **“SmartyCam Function setting”** to set **SmartyCam** channels (refer to **Race Studio Configuration** manual for more details).



- transmit the configuration to **AIM** logger clicking **“Transmit”** (see below).



**Note: it is suggested to disable non-used channels (see image above).**

## 5.2 – Communication protocol

Channels received by AIM loggers using Clusters 08-09 protocol are:

| <b>ID</b> | <b>CHANNEL NAME</b> | <b>FUNCTION</b>            |
|-----------|---------------------|----------------------------|
| ECU_1     | CU_SPEED            | Speed                      |
| ECU_3     | CU_RPM              | Engine speed               |
| ECU_4     | CU_FUEL_IST         | Fuel level                 |
| ECU_5     | CU_FUEL_AVE         | Fuel average               |
| ECU_6     | CU_ENGT             | Engine coolant temperature |
| ECU_7     | CU_SF_LIGHT1        | Shift light 1              |
| ECU_8     | CU_SF_LIGHT2        | Shift light 2              |
| ECU_9     | CU_SF_LIGHT3        | Shift light 3              |
| ECU_10    | CU_MIL_LIGHT        |                            |
| ECU_11    | CU_OIL_LIGHT        | Oil light                  |
| ECU_12    | CU_TC_LIGHT         | Traction control light     |
| ECU_15    | CU_SERV_LIGHT       |                            |
| ECU_19    | CU_TH2O_LIGHT       |                            |
| ECU_23    | CU_SEL_LTC          |                            |
| ECU_24    | OBD_PPS             | Pedal Position sensor      |
| ECU_25    | OBD_TPS             | Throttle Position Sensor   |
| ECU_26    | OBD_IAT             | Intake Air Temperature     |
| ECU_27    | OBD_MAF             | Mass Air Flow              |

## Chapter 6 – Europa 2006+ and Elise S2 Rover 2001-2004

Europa since 2006 and Elise S2 Rover from 2001 to 2004 only work with Kline protocol.

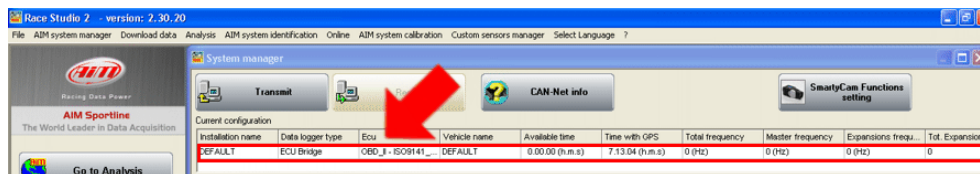
### 6.1 – Software configuration setting

Once **ECU Bridge** is connected, it is necessary to configure it in **Race Studio 2** software. Please refer to Chapter 1 to check which is the appropriate communication protocol. Then:

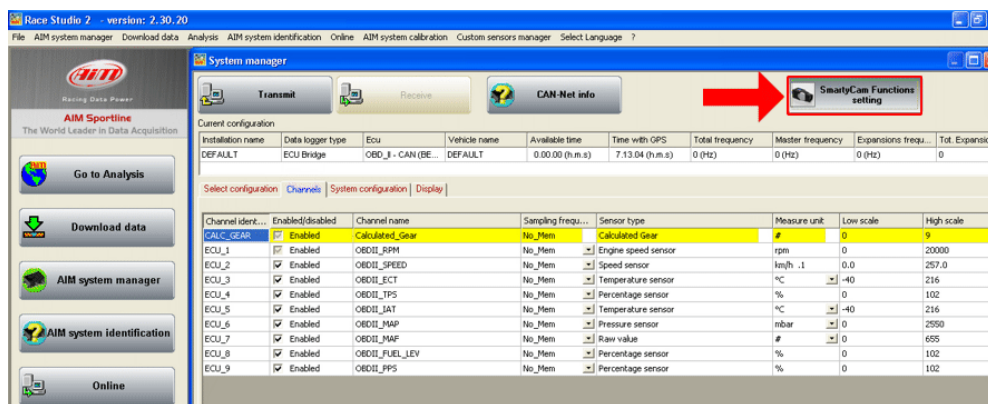
- Launch **Race Studio2 Configuration** Software
- Create a configuration pressing **“New”**.



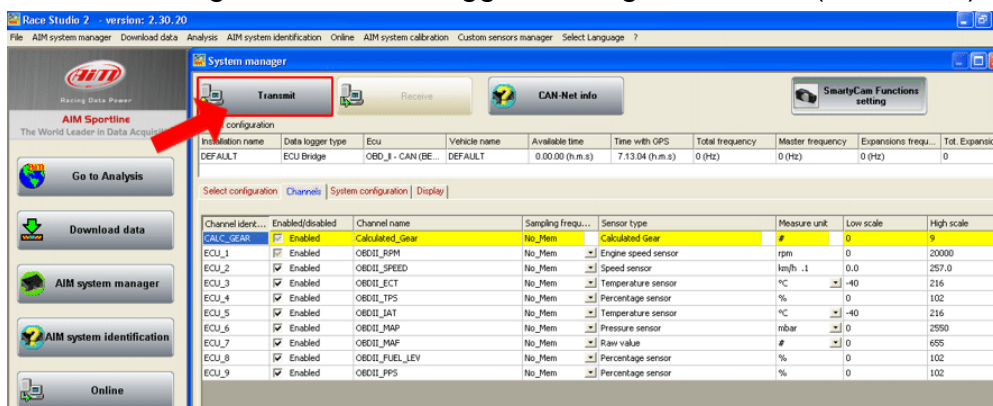
- select from **“ECU manufacturer”** menu: **“OBD\_II”**;
- to configure Europa, select from **“ECU Model”** menu: **“KWP2000\_FAST\_INIT”**.
- to configure Elise S2 Rover, select from **“ECU Model”** menu: **“ISO9141/2”**.



- Select **“SmartyCam Function setting”** to set **SmartyCam** channels (refer to **Race Studio Configuration** manual for more details).



- transmit the configuration to **AIM** logger clicking **“Transmit”** (see below).



**Note: it is suggested to disable non-used channels (see image above).**

## 6.2 – Communication protocol

Channels received by **AIM** loggers connected to OBDII are:

| <b>ID</b> | <b>CHANNEL NAME</b> | <b>FUNCTION</b>            |
|-----------|---------------------|----------------------------|
| ECU_1     | OBDII_RPM           | Engine Speed               |
| ECU_2     | OBDII_SPEED         | Speed Value                |
| ECU_3     | OBDII_ECT           | Engine Coolant Temperature |
| ECU_4     | OBDII_TPS           | Throttle Position Sensor   |
| ECU_5     | OBDII_IAT           | Intake Air Temperature     |
| ECU_6     | OBDII_MAP           | Manifold Absolute Pressure |
| ECU_7     | OBDII_MAF           | Mass Air Flow              |
| ECU_8     | OBDII_FUEL_LEV      | Fuel Level                 |
| ECU_9     | OBDII_PPS           | Pedal Position Sensor      |

**Note: all the above channels are managed by AIM OBDII. Please consider that acquired channels depend on the car model; for this reason some of them could not be available. Moreover it is suggested to disable the error channels to allow a faster data transmission.**

## Chapter 7– Evora since 2009

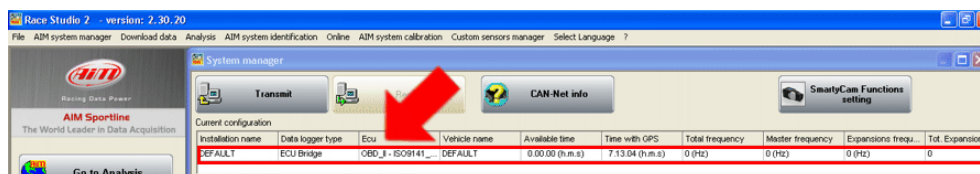
### 7.1 – Software configuration setting

Once **ECU Bridge** is connected, it is necessary to configure it in **Race Studio 2** software. Please refer to Chapter 1 to verify which is the appropriate communication protocol. Then:

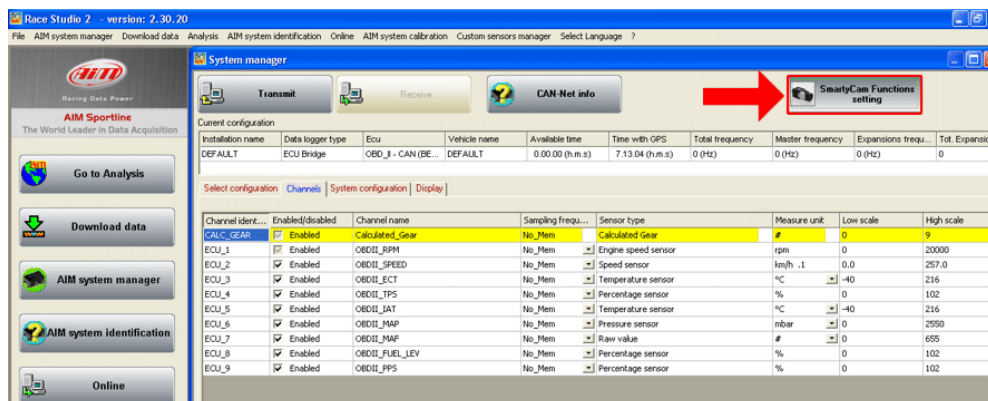
- Launch **Race Studio2 Configuration** Software
- Create a configuration pressing **“New”**.



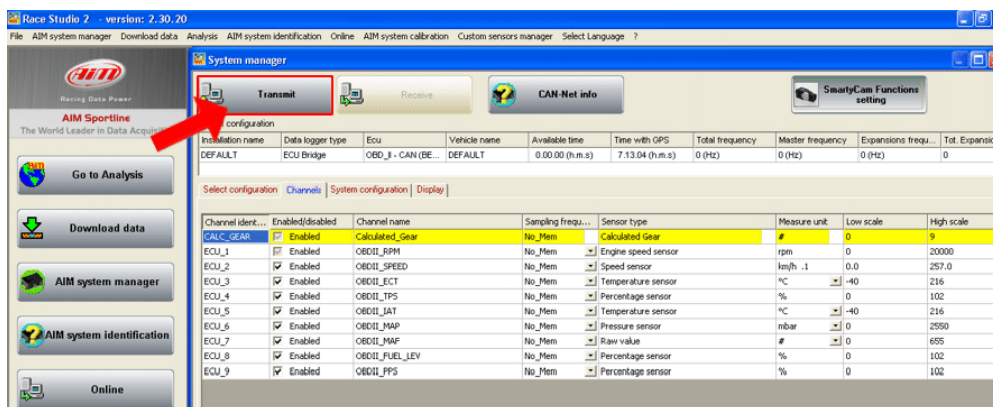
- select from **“ECU manufacturer”** menu: **“OBD\_II”**;
- select from **“ECU Model”** menu: **“CAN”**.



- Select **“SmartyCam Function setting”** to set **SmartyCam** channels (refer to **Race Studio Configuration** manual for more details).



- transmit the configuration to **AIM** logger clicking **“Transmit”** (see below).



**Note: it is suggested to disable non-used channels (see image above).**

## 7.2 – Communication protocol

Channels received by **AIM** loggers connected to OBDII are:

| <b>ID</b> | <b>CHANNEL NAME</b> | <b>FUNCTION</b>            |
|-----------|---------------------|----------------------------|
| ECU_1     | OBDII_RPM           | Engine Speed               |
| ECU_2     | OBDII_SPEED         | Speed Value                |
| ECU_3     | OBDII_ECT           | Engine Coolant Temperature |
| ECU_4     | OBDII_TPS           | Throttle Position Sensor   |
| ECU_5     | OBDII_IAT           | Intake Air Temperature     |
| ECU_6     | OBDII_MAP           | Manifold Absolute Pressure |
| ECU_7     | OBDII_MAF           | Mass Air Flow              |
| ECU_8     | OBDII_FUEL_LEV      | Fuel Level                 |
| ECU_9     | OBDII_PPS           | Pedal Position Sensor      |

**Note: all the above channels are managed by AIM OBDII. Please consider that acquired channels depend on the car model; for this reason some of them could not be available. Moreover it is suggested to disable the error channels to allow a faster data transmission.**

## Appendix – Part numbers

### Kit:

ECU Bridge OBDII with lighter plug: **X90BGCK12**

SmartyCam with 2m CAN cable: **X90SMYCEC2**

SmartyCam with 4m CAN cable: **X90SMYCEC4**

### Optional:

Suction cup kit: **X9KSSMC1**

Roll bar kit: **X9KSSMC0**

CAN cable with external microphone: **V02566100**