

AiM InfoTech

K-M-P - GCU2

Release 1.00



1

Software configuration

This document explains how to connect third party CAN expansion modules to AiM devices CAN2 bus.

The driver here documented allows to read data from a K-M-P GCU-2 module programmed with default settings on the calibration software K-M-P GCU-2 interface. To correctly communicate with the AiM device, it is necessary to check if the module is set with the following default parameters. Refer to the manufacturer for additional details on the configuration procedure.

Baudrate: **1Mbit/s (1000kbit/s)**

CAN ID 1: **2000 (0x7D0)**

CAN ID 2: **2001 (0x7D1)**

CAN ID 3: **2002 (0x7D2)**

CAN ID 4: **2003 (0x7D3)**

CAN ID 5: **2004 (0x7D4)**

Please note: In case this module is going to be used with different parameters, the user can set up a custom driver from the **CAN Protocols** section of the AiM configuration software Race Studio 3. Check the dedicated manual from the AiM website www.aim-sportline.com, Documentation – Firmware/Software area.

2 Wiring connection

These modules feature a bus communication protocol based on CAN, this data stream is accessible through a 2-way DTM06-2S-E007 connector (right picture below) located on the universal loom or through the main 37-way connector of the GCU-2. In this case the mating part AS614-35SN is pictured below (left), and the connection table for both options follows.



35-pin Deutsch
Pin nr
 10
 11

2-pin Deutsch
Pin nr
 1
 2

Function
 CAN High
 CAN Low

**AiM wire label
 (optional harness)**
 CAN2 +
 CAN2 -

3 AiM device configuration

Before connecting the kit to the AiM device set this up using AiM Race Studio software. The parameters to select in the device configuration are:

- ECU manufacturer: **KMP**
- ECU Model: **GCU2** (Only RS3 – CAN2 Stream)

If there is only the AiM device connected to this module, enable the CAN Bus 120 Ohm Resistor.

<input checked="" type="checkbox"/>	Enable the CAN Bus 120 Ohm Resistor
<input type="checkbox"/>	Silent on CAN Bus

4 “KMP – GCU2” protocol

Channels received by AiM loggers configured with “KMP - GCU2” protocol are:

CHANNEL NAME	FUNCTION
GEAR POT	Gear potentiometer voltage
SYS PRESSURE	System pressure
COMP TEMP	Compressor temperature
ERROR CODE CNT	Error code counter
ERR CODES	Error code
UP	Upshift valve
DOWN	Downshift valve
BLIP	Blip valve
IGN CUT	Engine cut active
COMPRESSOR	Compressor active



VP SWITCH	Paddle switch
EMERG SW	Emergency switch active
VC GEAR	Gear number
VC RPM	RPM
RPM Vx	Downshift RPM
TPS	Throttle position
NEUTRAL	Neutral switch active
SHIFT STATUS	Shift status
AUTOCALIB ST	Autocalibrationstatus
CLUTCH FLAG	Clutch active
CLUTCH PRESS	Clutch pressure
AUTOSHIFT FLAG	Autoshift flag
SHIFT LIGHT	Shift light active
VEH SPEED	Vehicle speed
CALC GEAR RATIO	Calculated gear ratio
SHF CHK FLAG	Shift check flag
REVERSE	Reverse switch active
BLIP LEV	Blip level (variable blip)
CAN OK	CAN-bus ok check
DEBUG MODE	Debug mode active